

**R** RENOWNED  
KNOW-HOW  
Automation Technology

**RK ROSE+KRIEGER**  
A Phoenix Mecano Company



**Multilift**  
Two-stage lifting column

# Two-stage lifting column - Multilift



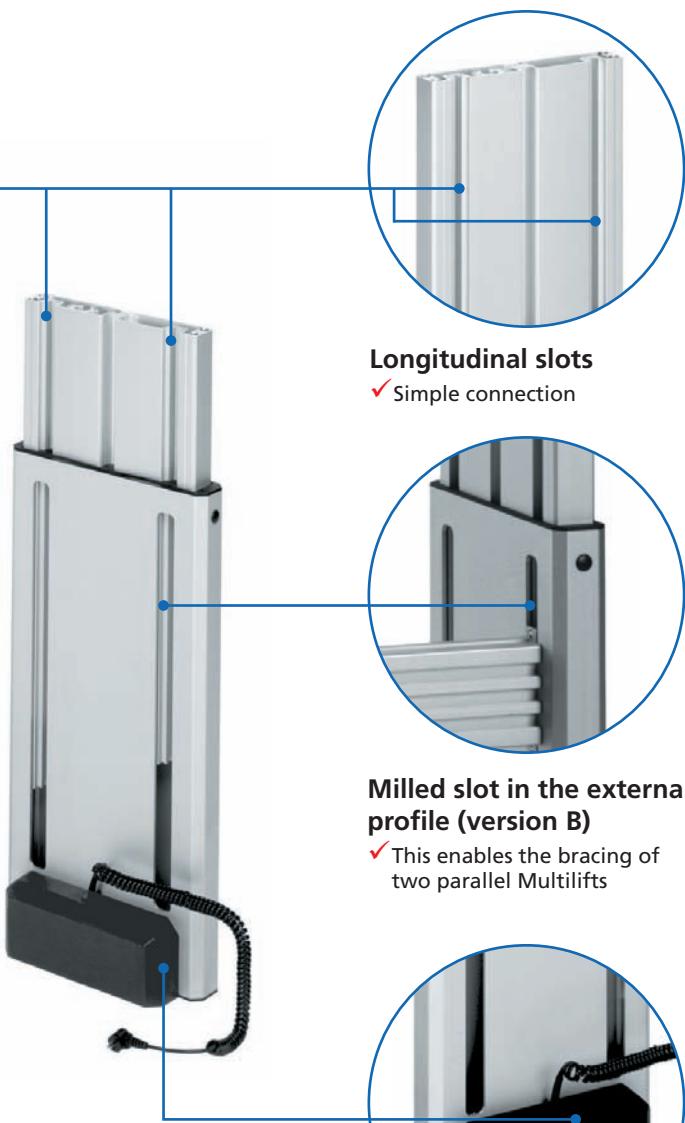
**Slimline design and and an unbeatable price/performance ratio**



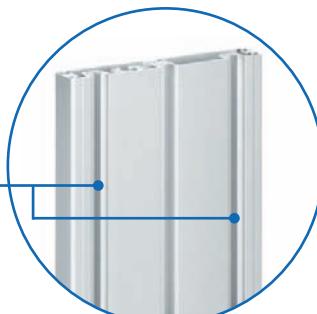
with interior carriage



Version A,  
without milled slot



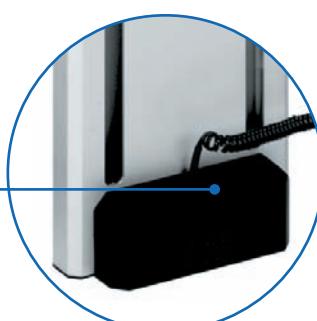
Version B,  
with milled slot in the  
external profile



**Longitudinal slots**  
✓ Simple connection



**Milled slot in the external  
profile (version B)**  
✓ This enables the bracing of  
two parallel Multilifts



**High-performance DC  
motor**  
✓ Single or synchronous  
control supported

## Features:

- Quadruple bearings with POM slide bearing shells
- High-performance DC motor
- Integrated limit switches
- Self-locking, even under max. load

## Options:

- Version with manual drive via crank handle
- Special stroke lengths
- Quadro control enables control of up to 32 columns synchron
- Tested to EN 60601-1 (3E)

## Multilift - Table of contents

<b>Properties / Technical data</b>	<ul style="list-style-type: none"> <li>■ General information/operating conditions Page 32</li> <li>■ Power diagram..... Page 32</li> <li>■ Load data..... Page 32</li> </ul>
<b>Versions</b> (Dimensions, order numbers)	<ul style="list-style-type: none"> <li>■ Multilift Mono und Synchro..... Page 34</li> <li>■ Multilift with internal carriage Mono und Synchro..... Page 36</li> <li>■ Multilift Synchronous package ..... Page 38</li> </ul>
<b>Accessories</b>	<b>Fixing</b> <ul style="list-style-type: none"> <li>■ Adaptor bar..... Page 39</li> <li>■ Assembly plate .....</li> <li>■ RK SyncFlex..... Page 41</li> <li>■ Foot..... Page 42</li> </ul>
	<b>Position determination</b> <ul style="list-style-type: none"> <li>■ Controls .....</li> <li>■ PLC/PC data interface..... Page 45</li> <li>■ Hand switches .....</li> </ul>
	<b>Lifting columns</b>
	<b>Electric cylinder</b>
	<b>Controls &amp; Accessories</b>
	<b>Appendix</b>
	<b>Introduction</b>

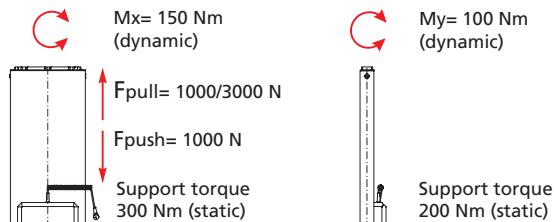
# Multilift – Technical data

## General information/operating conditions

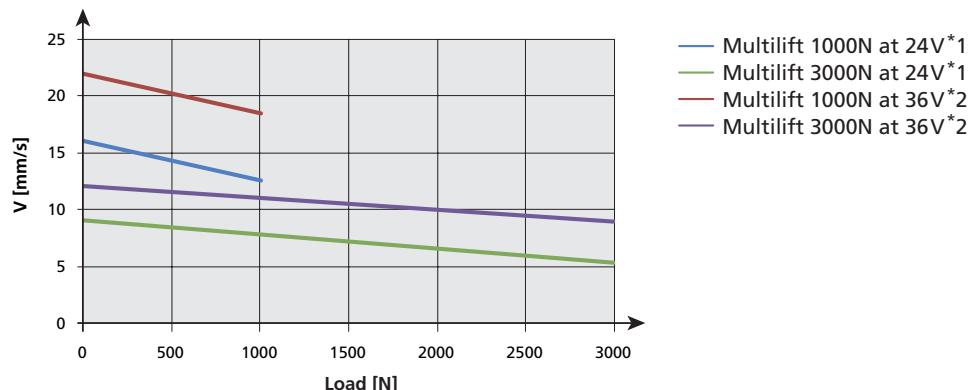
Type	Multilift	Multilift S
Design	Slim lifting column	
Guide	Quadruple bearings with POM slide bearing shells	
Installation position	Any position / suspended with drop protection provided by the customer	
Push force*	3.000 N	1.000 N
Pull force*	1000 N (only in conjunction with factory-mounted base plate)	
Max. speed	8 mm/s	16 mm/s
Voltage	24 V DC	
Power input	120 W	
Protection class	IP 20 / IP10 for version B (with milled slot)	
Self-locking	3.000 N	1.000 N
Ambient temperature	+5°C to +40°C	
Displacement during synchronous operation	0-2 mm	0-4 mm
Duty cycle	At nominal load, 10% (max. 2 mins operating time, 18 mins rest time)	

\* In medical applications, the maximum pull force of 500 N and, in the case of the version with a travel speed of 8 mm/s, the maximum push force of 2000 N must not be exceeded.

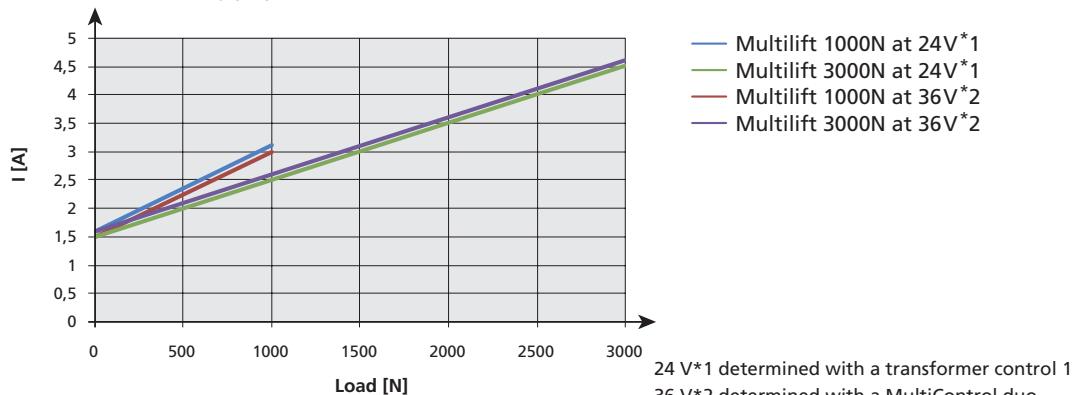
## Load data



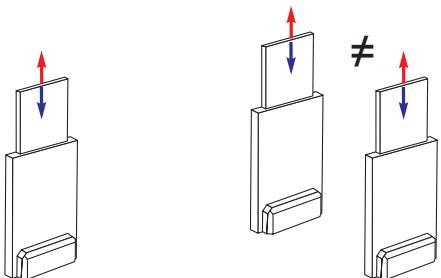
## Speed/Force diagram



## Current consumption/Force diagram



## Multilift Mono

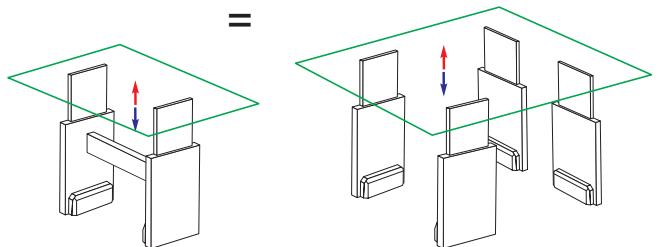


1-2 Multilifts in single or parallel operation

## Parallel operation

The standard version also supports parallel operation of two Multilifts (no synchronisation). This may produce different lifting positions during operation, which can be levelled out by moving to the end positions.

## Multilift Synchro



2-4 Multilifts in synchronous operation

## Synchronous operation

Synchronous operation of two or more columns. In conjunction with the integrated sensors, the control (see page 44) ensures synchronisation, and thus constant alignment of all the columns in both directions of travel, even if subject to different loads. The synchronous operation tolerance depends on the lifting speed and is max 2 mm on the 8 mm/s version and max 4 mm on the 16 mm/s version. A memory function is also available.

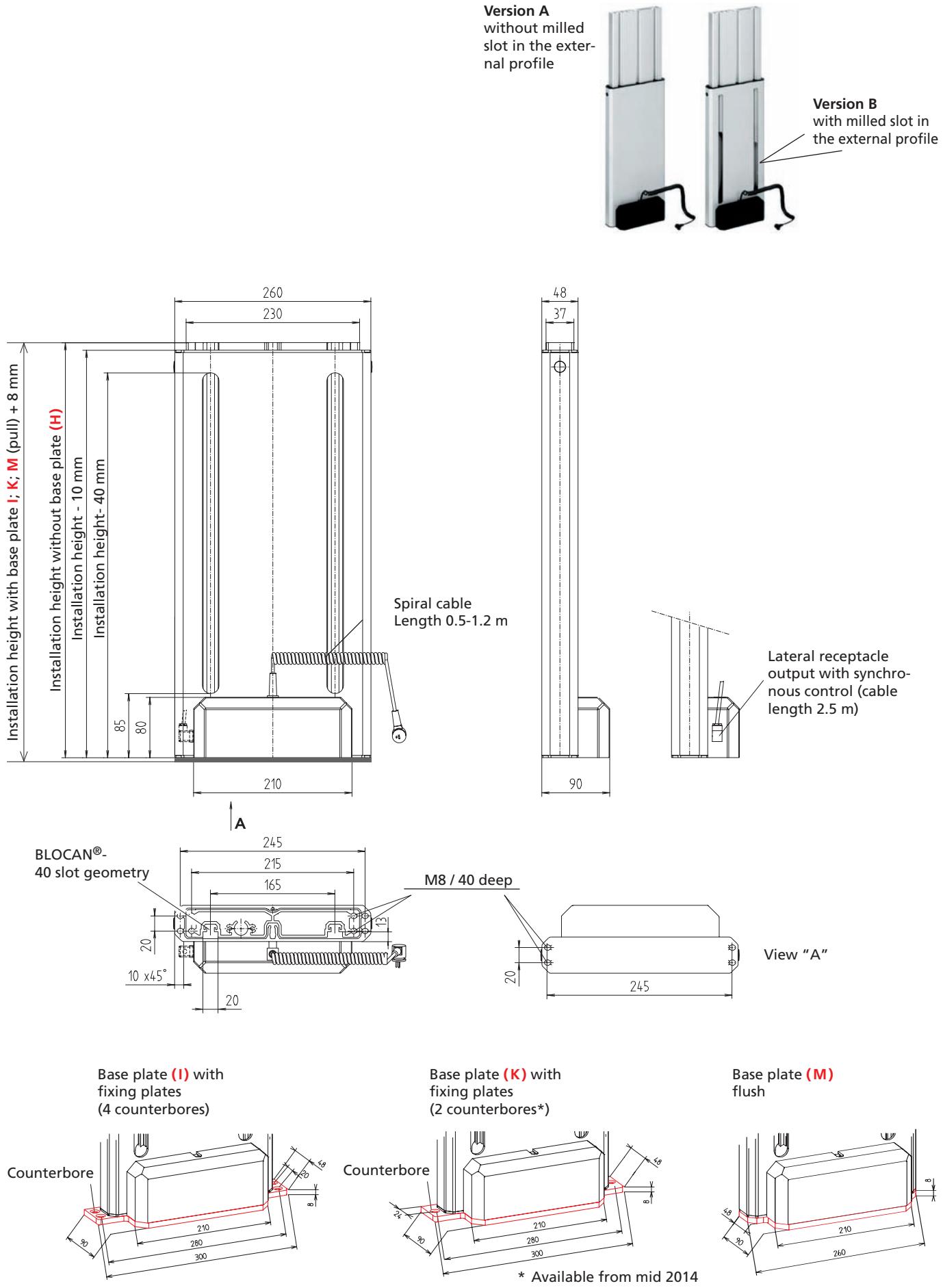


Universal Table Ironing Machine

Height-adjustable assembly workplaces



# Multilift - Versions



## Multilift – Versions

### Multilift Mono



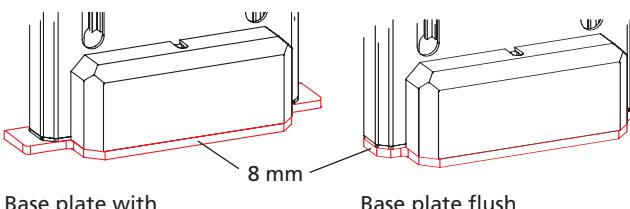
Code No.	Type	max. push force [N]	max. pull force [N]	Total travel [mm]	Installation height without base plate [mm]	Weight [kg]
QAB13_G0_0355	Multilift 350	3.000 / 2.000 (med.)	1.000 / 500 (med.)	355	550	9,1
QAB13_G0_0400	Multilift 400			400	595	10,0
QAB13_G0_0450	Multilift 450			452	650	10,8
QAB13_G0_0500	Multilift 500			498	695	11,5
QAB26_G0_0355	Multilift 350 s	1.000 / 1.000 (med.)	1.000 / 500 (med.)	355	550	9,1
QAB26_G0_0400	Multilift 400 s			400	595	10,0
QAB26_G0_0450	Multilift 450 s			452	650	10,8
QAB26_G0_0500	Multilift 500 s			498	695	11,5

**Version:**

- 1 = B (with milled slot in the external profile)  
 2 = A (without milled slot in the external profile)

**Base plate (For dimensions, see page 34):**

- H** = without base plate  
 (not suitable for pull forces)  
**I** = with external fixing plates  
 4 counterbores  
**K** = with external fixing plates  
 2 counterbores\*  
**M** = base plate flush



### Multilift Synchro



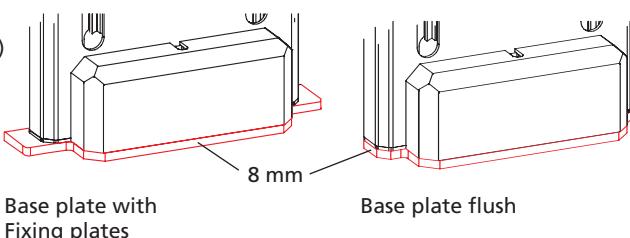
Code No.	Type	max. push force [N]	max. pull force [N]	Total travel [mm]	Installation height incl. base plate [mm]	Weight [kg]
QAB13_G0_0355	Multilift 350	3.000 / 2.000 (med.)	1.000 / 500 (med.)	355	558	10,1
QAB13_G0_0400	Multilift 400			400	603	11,0
QAB13_G0_0450	Multilift 450			452	658	11,8
QAB13_G0_0500	Multilift 500			498	703	12,5
QAB26_G0_0355	Multilift 350 s	1.000 / 1.000 (med.)	1.000 / 500 (med.)	355	558	10,1
QAB26_G0_0400	Multilift 400 s			400	603	11,0
QAB26_G0_0450	Multilift 450 s			452	658	11,8
QAB26_G0_0500	Multilift 500 s			498	703	12,5

**Version:**

- 3 = B (with milled slot in the external profile)  
 4 = A (without milled slot in the external profile)

**Base plate (For dimensions, see page 34):**

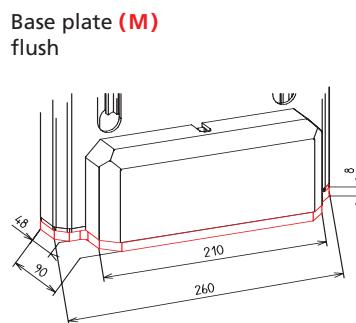
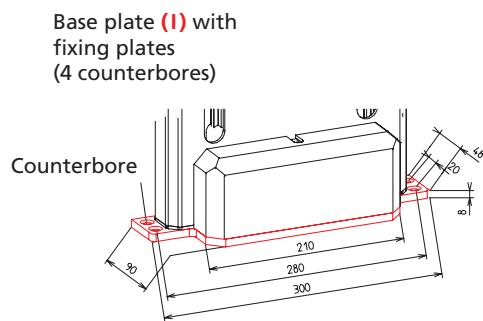
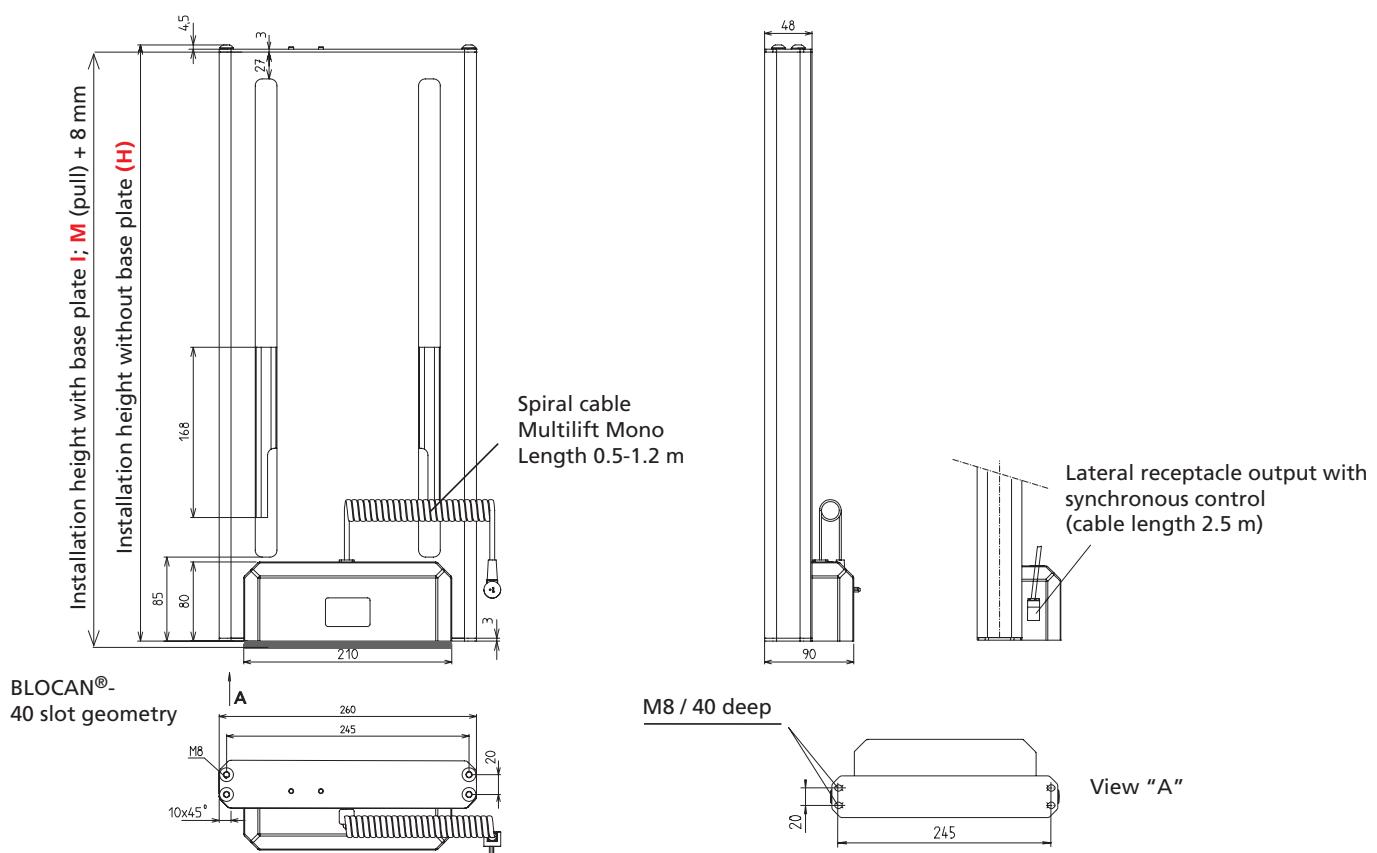
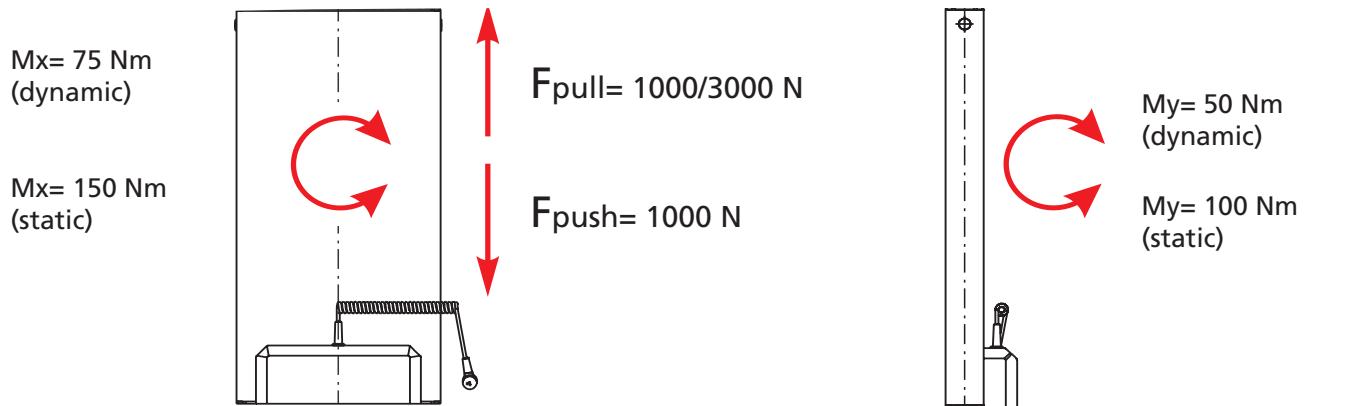
- I** = with external fixing plates  
 4 counterbores  
**K** = with external fixing plates  
 2 counterbores\*  
**M** = base plate flush



\* Available from mid 2014

# Multilift – Technical data - internal carriage

## Load data with internal carriage



## Multilift – Versions

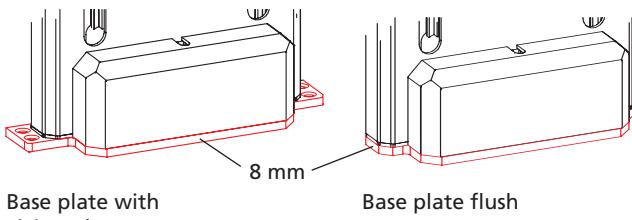
### Multilift Mono



Code No.	Type	max. push force [N]	max. pull force [N]	max. Hubgeschw. [mm/s]	Total travel [mm]	Installation height without base plate [mm]	Weight [kg]
QAB13_G070355	Multilift 350	3.000 / 2.000 (med.)	1.000 / 500 (med.)	8	355	557,5	6,4
QAB13_G070400	Multilift 400				400	602,5	6,7
QAB13_G070450	Multilift 450				452	657,5	7,1
QAB13_G070500	Multilift 500				498	702,5	7,4
QAB26_G070355	Multilift 350 s	1.000 / 1.000 (med.)	1.000 / 500 (med.)	16	355	557,5	6,4
QAB26_G070400	Multilift 400 s				400	602,5	6,7
QAB26_G070450	Multilift 450 s				452	657,5	7,1
QAB26_G070500	Multilift 500 s				498	702,5	7,4

Base plate (For dimensions, see page 36):

- H** = without base plate  
(not suitable for pull forces)
- I** = with external fixing plates  
4 counterbores
- M** = base plate flush



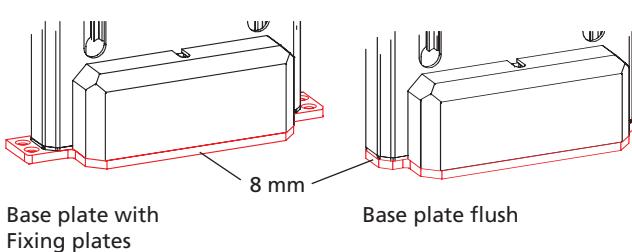
### Multilift Synchro



Code No.	Type	max. push force [N]	max. pull force [N]	max. Hubgeschw. [mm/s]	Total travel [mm]	Installation height incl. base plate [mm]	Weight [kg]
QAB13_G080355	Multilift 350	3.000 / 2.000 (med.)	1.000 / 500 (med.)	8	355	565,5	6,4
QAB13_G080400	Multilift 400				400	610,5	6,7
QAB13_G080450	Multilift 450				452	665,5	7,1
QAB13_G080500	Multilift 500				498	710,5	7,4
QAB26_G080355	Multilift 350 s	1.000 / 1.000 (med.)	1.000 / 500 (med.)	16	355	565,5	6,4
QAB26_G080400	Multilift 400 s				400	610,5	6,7
QAB26_G080450	Multilift 450 s				452	665,5	7,1
QAB26_G080500	Multilift 500 s				498	710,5	7,4

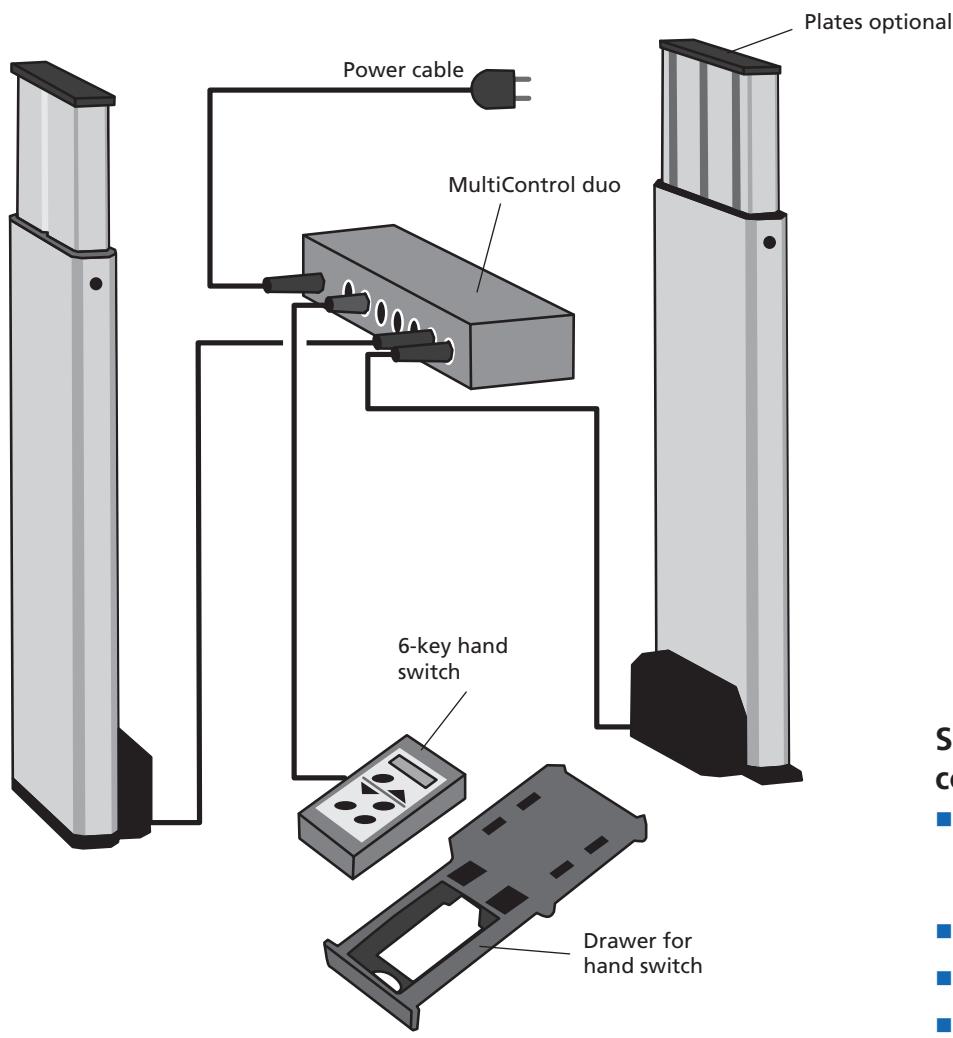
Base plate (For dimensions, see page 36):

- I** = with external fixing plates  
4 counterbores
- M** = base plate flush



# Multilift – Synchronous package

Buying made simple – the complete plug and play system



## Synchronous package comprises:

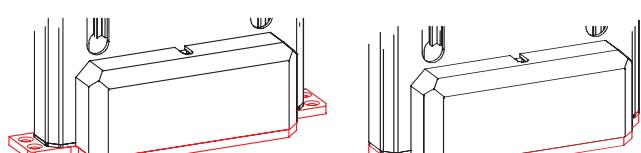
- Two Multilifts  
(without milled slot – version A/  
with milled slot – version B)
- MultiControl duo
- 6-key hand switch (memory)
- Drawer for hand switch
- Plug & play  
(factory-initialised)

## Multiliftsystem Synchro

Code No.	Type	max. push force [N]	max. pull force [N]	max. Hubgeschw. [mm/s]	Total travel	Installation height incl. base plate [mm]
QBB13_G0_0355	Multiliftsystem Synchro	3.000	1.000	8	355	558
QBB13_G0_0400	Multiliftsystem Synchro				400	603

**Version:**  
3 = B (with milled slot in the external profile)  
4 = A (without milled slot in the external profile)

**Base plate:**  
**I** = with external fixing plates  
4 counterbores  
**M** = base plate flush

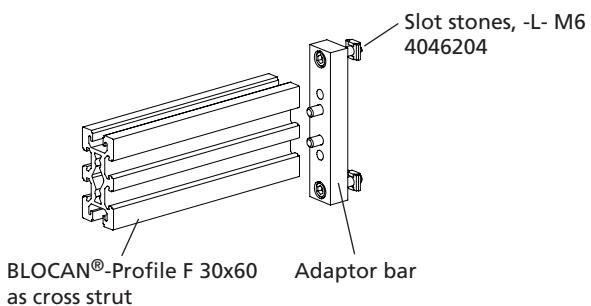


Base plate with fixing plates

Base plate flush

## Adaptor bar

- Cross struts from the BLOCAN® Profile Assembly System are used to increase the stability of two version B Multilifts (see page 34). The adaptor bar is suitable for F profile 40 x 80 L and F 30x60.



Code No.	Version
QZD020020	Adaptor bar for BLOCAN® profiles
4285000	Profile* F-40 x 80-L, can be cut to specification



Length (clear width between the Multilifts -2 mm)

---

\* For dimensions of the profiles, please refer to the catalogue  
BLOCAN PROFILE TECHNOLOGY

# Multilift – Fixing

## Multilift assembly plates / thrust compression plate

The "top" and "bottom" assembly plates facilitate the installation of the Multilift in the customer application (no pull force).

The thrust compression plate (or bottom assembly plate) is required if the substrate cannot absorb the push forces (no pull force).

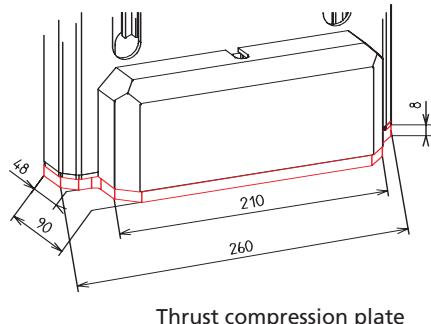
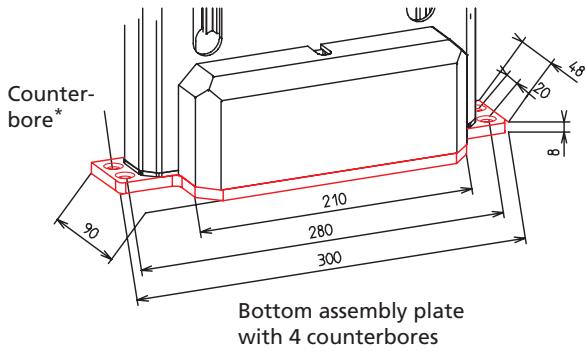
**Material:** Die-cast, black powder-coated galvanised fixing set

**Scope of delivery:** 1x assembly or thrust compression plate fixing set

### Note:

The "bottom" assembly plates listed here and the thrust compression plate are only suitable for push loads.

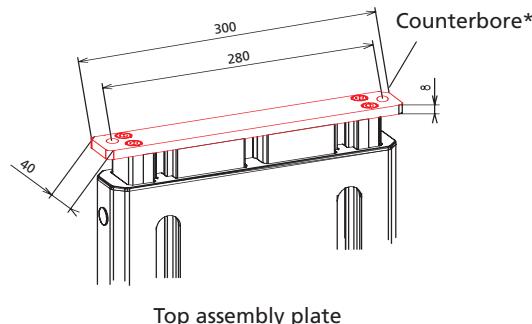
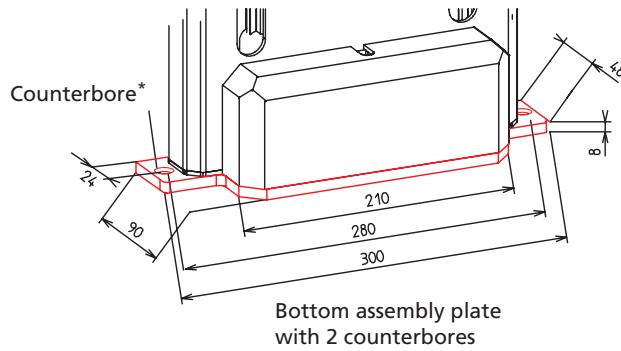
For applications involving pull force and in synchronised groups, a base plate – factory-mounted on the Multilift – must be used. These versions are defined by the Code No. (Page 35/37)



The supporting surfaces for fixing the internal and external profile must be flat. Since the drive motor is supported by the plastic housing, the entire surface of the Multilift must rest on a stable substructure. This can be achieved by using the "top" and "bottom" assembly plates, which are specially designed for this purpose, or by full-surface fixing to a solid substrate.

The M8 fixing screws are screwed into the screw channels. A minimum depth of penetration of 20 mm in the internal and external profile must be ensured.

In the case of repeated installation, a minimum depth of penetration of approx. 40 mm is recommended!



\* DIN 74 - F8

Code No.	Version
QZD020023	Bottom assembly plate with 4 counterbores
QZD020024	Bottom assembly plate with 2 counterbores*
QZD020025	Thrust compression plate
QZD020549	Top assembly plate*

\* Available from mid 2014

## Multilift – Fixing

### RK SyncFlex H

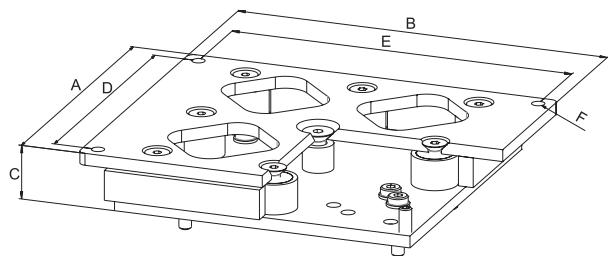
**Scope of delivery:**  
Adjuster plate, incl. fixing material



#### Horizontal alignment

- To prevent locked-up stress in mechanically overdefined bearing systems (more than one fixed bearing) around the horizontal axis.  
With RK SyncFlex H defined loose bearings supplement the application.

- The horizontal compensation in the Z-axis enables the freedom of movement required when moving the lifting columns.



[mm]

Code No.	Type	A	B	C	D	E	F
QZD020471	MultiLift	70	280	36	40	260	M 10

### RK SyncFlex V

**Scope of delivery:**  
Adjuster plate, incl. fixing material

**Option:**  
Optionally available with or without pressure plate (see table)

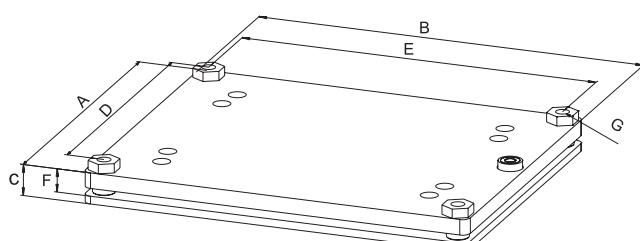


#### Vertical alignment

- If the lifting columns are not parallel, the distance between the two upper fixing points will change during the movement. However, a rigid connection keeps this distance constant, and this means that the lifting columns are subject to very strong forces.

RK SyncFlex V enables the compensation of unevenness in the mounting environment.

- The lifting columns can be aligned via the vertical adjustment around the X-Y axes.



[mm]

Code No.	Type	A	B	C	D	E	F	G
<b>Without pressure plate</b>								
QZD020472	MultiLift	110	300	-	90	280	10-15	M 10
<b>With pressure plate</b>								
QZD020462	MultiLift	110	300	15-20	90	280	10-15	M 10

# Multilift – Fixing

## Foot

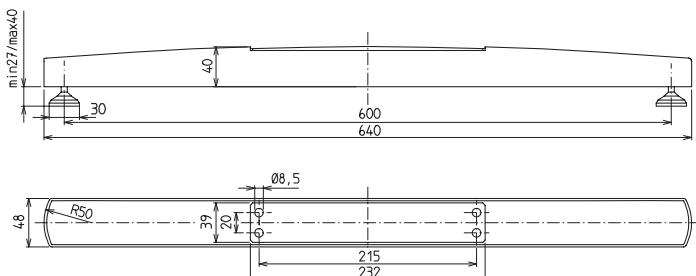
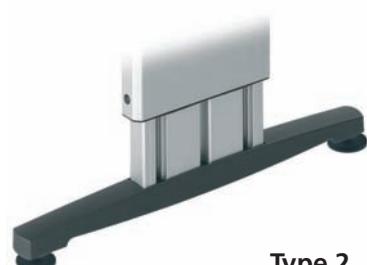
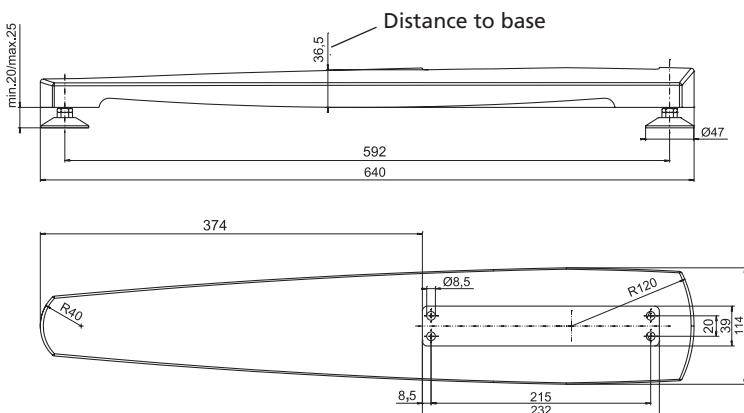
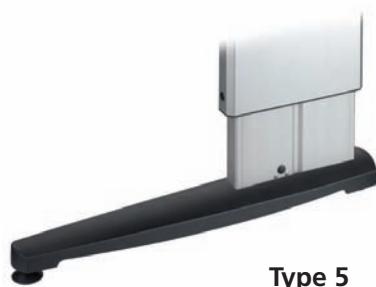
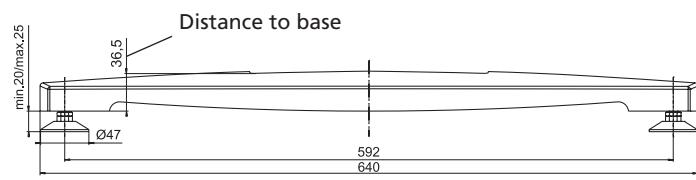
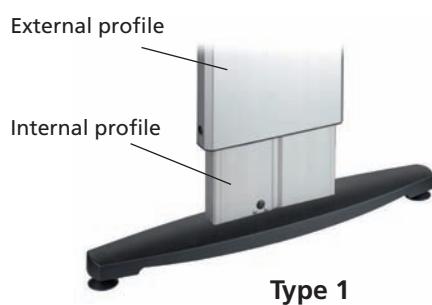
- Different foot versions for the Multilift
- No modifications to the Multilift required
- Max. load 1,000 N

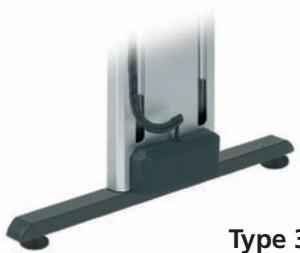
## Material:

Type 1/2/5 GK-AlSi12/3.2583.02,  
black powder-coating

Type 3/4 steel tube, ends capped  
black powder-coating

**Scope of delivery:**  
one foot with fixing set

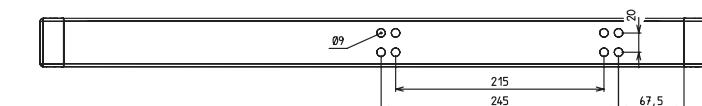
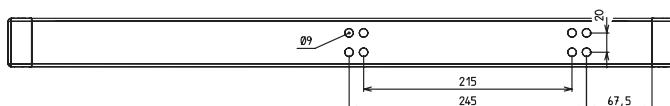
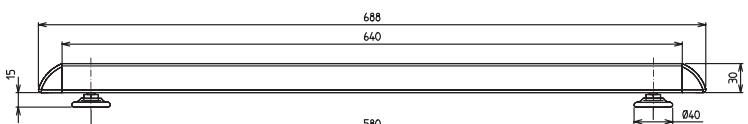
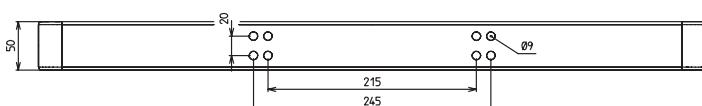
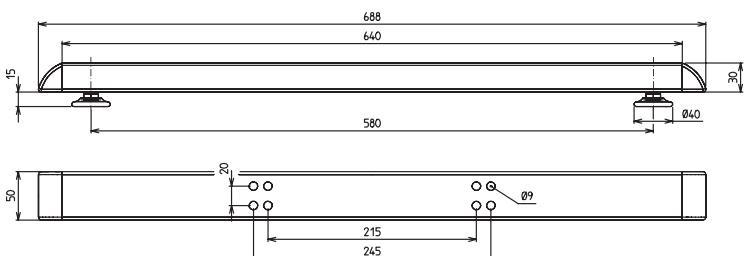


**Type 3**

Multilift centrally mounted  
(choice of internal or external  
profile)

**Type 4**

Multilift mounted off-centre  
(choice of internal or external  
profile)



Code No.	Type
QZD020252	1
QZD020253	2
QZD020254	3
QZD020255	4
QZD020343	5

# Multilift – Drive / Accessories

## Controls

- Input voltage 230 V AC
- Output voltage 24/36 V DC
- For battery operated controls

### Order information:

Observe the current consumption of the drives when selecting the control.

Transformer control 120 VA



approx. 24 V DC

MultiControl



approx. 36 V DC

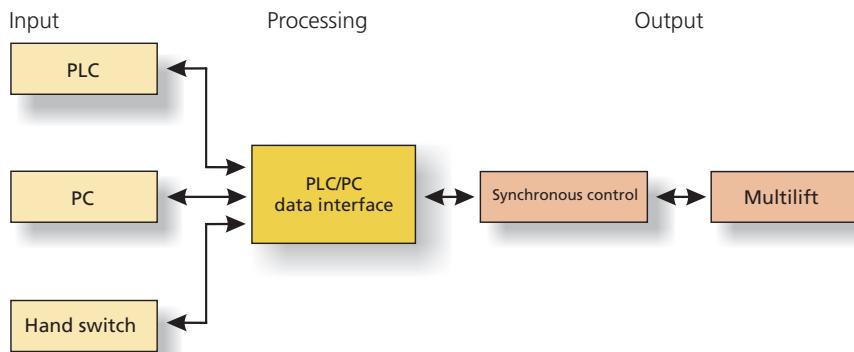
For dimensions and other technical data, please refer to the chapter „Motors and controls“

Code No.	Version	
<b>Controls for Multilift mono</b>		
QZA07C13AX021	Transformer control 120 VA connection A, up to max. 3 A current output, 24 V DC	Controls up to 2 drives
QSTAACA1AA000	MultiControl mono connection A, up to max. I= 10 A current consumption, 24 V DC	Controls up to 2 drives
<b>Controls for Multilift synchro</b>		
QST10C02AA000	MultiControl duo connection C, up to max. 12 A current output, 36 V DC	Controls up to 2 drives synchronous
QST10C04AA000	MultiControl quadro connection C, up to max. 12 A current output, 36 V DC	Controls up to 4 drives synchronous
<b>Accessories</b>		
QZD020083	Fixing plate 120 VA, control is pushed onto the plate	
QZD100093	6 m bus cable for the networking of up to 8 synchronous controls	
QZD0702844000*	Straight connecting cable (4 m) with 5-pin connector and open cable end	
QZD070525	Extension cable 2,5 m drive for connector A/2-pin DIN socket	
QZD070526	Extension cable 2,5 m drive for connector C/8-pin DIN socket	

\*for the connection of a parallel hand switch or an external potentiometer (in the case of the MultiControl mono)

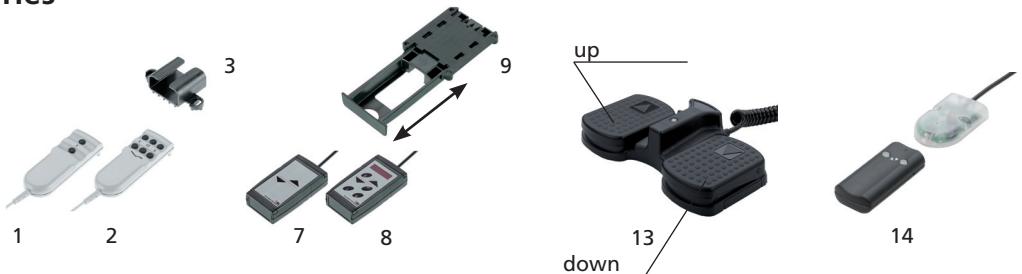
## PLC/PCdata interface

- This interface enables actuation of the synchronous control system via different input devices (PLC, PC and hand switch)
- You will find further product information on page 182



Code No.	Type
QZD100108	PLC/PC data interface
QZD100110	Wall strap for mounting in a control cabinet

## Hand switches/accessories



Code No.	Version	Fig.
<b>Hand switch for transformer control</b>		
QZB02C03AD031	Hand switch with 1 m spiral cable – 6 function keys	2
<b>Hand switches for transformer or synchronous control</b>		
QZB02C03AB031	Hand switch with 1 m spiral cable – 2 function keys	1
QZB00D04AB041	Hand switch with 1 m spiral cable – 2 function keys	7
QZB02C01AE114	Foot switch – 2 function keys	13
QZB00D07BK141	Wireless hand switch – 2 function keys	14
<b>Hand switch for synchronous control</b>		
QZB00D04AD041	Hand switch with 1 m spiral cable – 6 function keys	8
<b>Accessories for hand switches</b>		
QZD000072	Bracket for hand switch: Fig. 1 + 2	3
QZD000074	Hand switch drawer: Fig. 7 + 8	9

**Note:**

For further hand switch versions, please refer to the chapter "Controls" on page 146

We say what we do - and do what we say!  
We also say what we can't do - and don't do it!



---

**Connecting and positioning systems**

RK Rose+Krieger GmbH  
Postfach 15 64  
D-32375 Minden  
Telephone: +49 (5) 71/9335-0  
Fax: +49 (5) 71/9335-119  
E-Mail: info@rk-online.de  
Internet: www.rk-rose-krieger.com